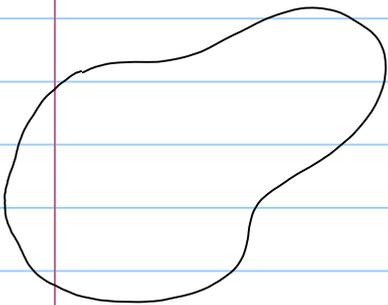


→ Length and cross-section!

$$L \gg D$$

→ one of the dimension (length) is much much greater than other two (cross-section)

$$\underline{\underline{L/D > 10}}$$

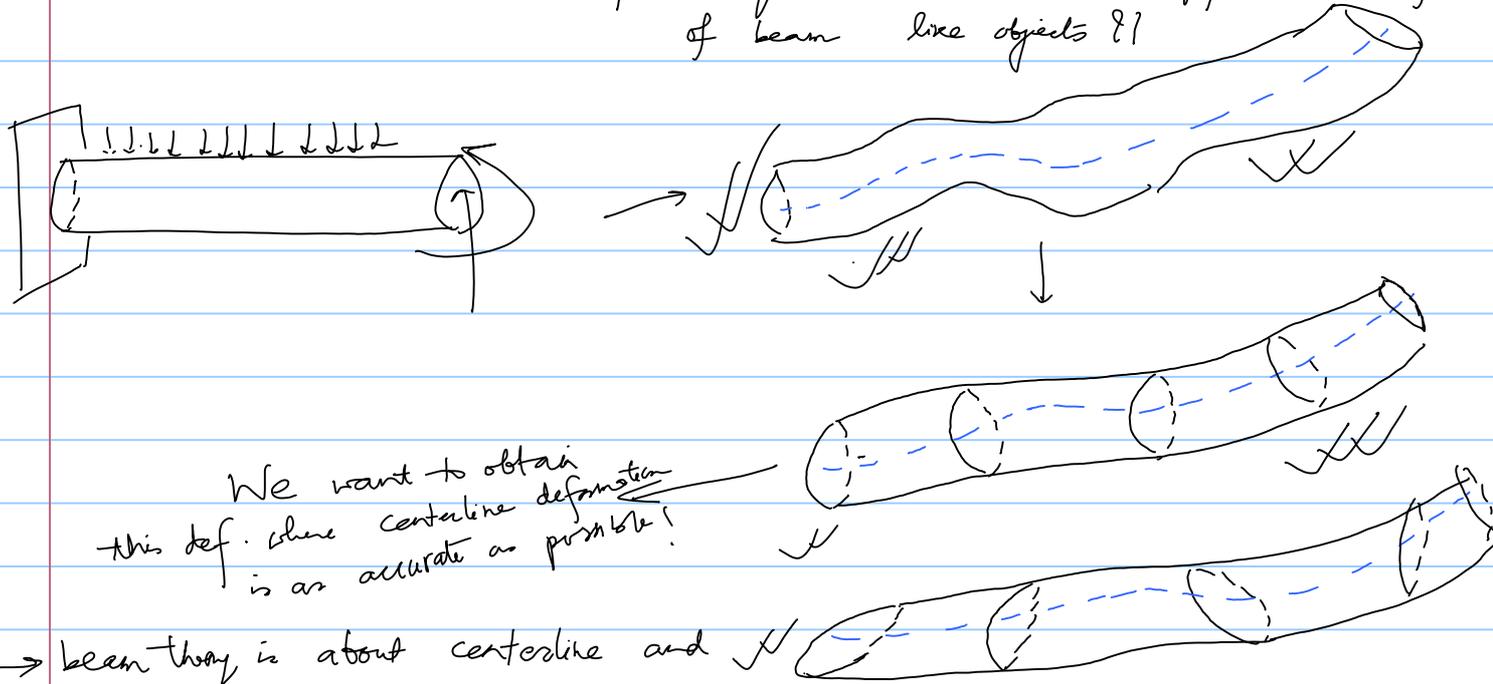


$$\frac{\partial \sigma_{11}}{\partial x_1} + \frac{\partial \tau_{12}}{\partial x_2} + \frac{\partial \tau_{13}}{\partial x_3} + b_1 = \rho a_1$$

BC.

Can be applied to beams also!

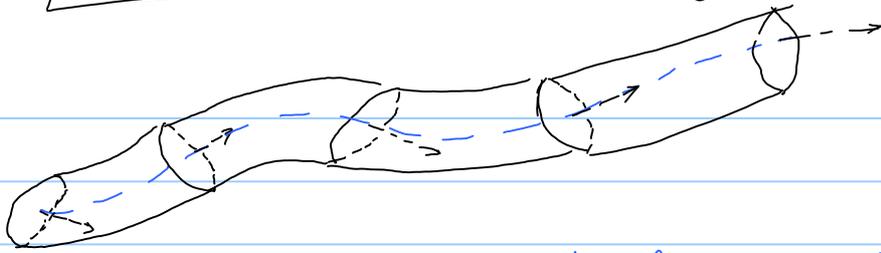
* Can we derive simpler equations to obtain approximate deformation of beam like objects?



We want to obtain this def. where centerline deformation is as accurate as possible!

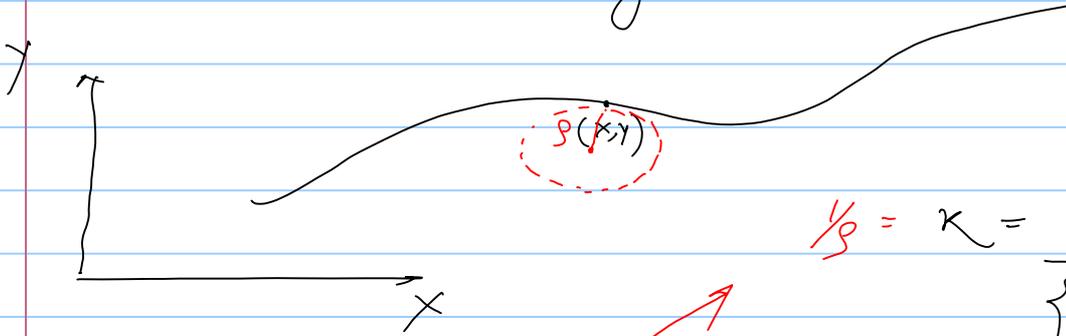
→ beam theory is about centerline and cross-section orientation!

Euler-Bernoulli beam theory



① → cross-section normal & centerline tangent are aligned!

→ centerline is the only unknown!



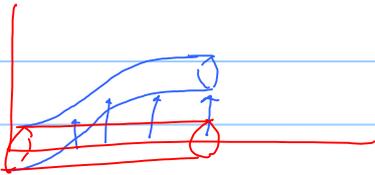
$$\frac{1}{\rho} = \kappa = \frac{\frac{d^2y}{dx^2}}{\left\{1 + \left(\frac{dy}{dx}\right)^2\right\}^{3/2}} = \frac{M}{EI}$$

Bending of beam
 $M = EI \kappa$

$$\Rightarrow EI \frac{\frac{d^2y}{dx^2}}{\left\{1 + \left(\frac{dy}{dx}\right)^2\right\}^{3/2}} = M$$

② $x \approx X$

$$\Rightarrow EI \frac{\frac{d^2y}{dX^2}}{\left\{1 + \left(\frac{dy}{dX}\right)^2\right\}^{3/2}} = M(X)$$



③

$$\left| \frac{dy}{dX} \right| \ll 1$$

$$1 + \left(\frac{dy}{dX}\right)^2 \approx 1$$

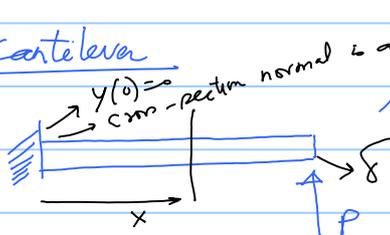
eq becomes linear in y

$$EI \frac{d^2y}{dX^2} = M(X)$$

linear & 2nd order

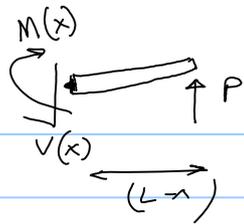
2 BCs + additional BC for unknown parameter in $M(X)$

A cantilever



cross-section normal is along x \Rightarrow centerline tangent is along x $\Rightarrow \frac{dy}{dx}(0) = 0$

→ First, we obtain bending moment profile



$$\Rightarrow -M(x) + P(L-x) = 0$$

$$\Rightarrow M(x) = P(L-x)$$

$$EI \frac{d^2y}{dx^2} = P(L-x) \Rightarrow \underline{\underline{2 \text{ B.C.D}}}$$

⇓

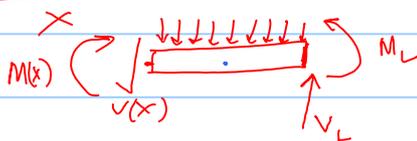
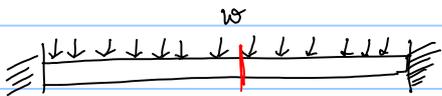
$$EI \frac{dy}{dx} = PLx - \frac{Px^2}{2} + C \Rightarrow C = 0$$

⇓

$$EI y = PL \frac{x^2}{2} - \frac{Px^3}{6} + D \Rightarrow D = 0$$

$$\Rightarrow y = \frac{PL^3}{6EI} \left(3 \frac{x^2}{L^2} - \frac{x^3}{L^3} \right)$$

$$\Rightarrow \delta = y(L) = \frac{PL^3}{3EI}$$



$$EI \frac{d^2y}{dx^2} = M(x)$$

$$\Rightarrow -M(x) + M_L + V_L(L-x) - \frac{w(L-x)^2}{2} = 0$$

$$\Rightarrow M(x) = M_L + V_L(L-x) - \frac{w(L-x)^2}{2}$$

$$EI \frac{d^2y}{dx^2} = M_L + V_L(L-x) - \frac{w(L-x)^2}{2}$$

2

4 B.C.s required \Rightarrow

$$y(0) = y(L) = 0$$

$$\frac{dy}{dx}(0) = \frac{dy}{dx}(L) = 0$$